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import array
import micropython
import utime
from machine import Pin
from micropython import const

class InvalidChecksum(Exception):
    pass

class InvalidPulseCount(Exception):
    pass

MAX_UNCHANGED = const(100)
MIN_INTERVAL_US = const(200000)
HIGH_LEVEL = const(50)
EXPECTED_PULSES = const(84)

class DHT11:
    _temperature: float
    _humidity: float

    def __init__(self, pin):
        self._pin = pin
        self._last_measure = utime.ticks_us()
        self._temperature = -1
        self._humidity = -1

    def measure(self):
        current_ticks = utime.ticks_us()
        if utime.ticks_diff(current_ticks, self._last_measure) <
MIN_INTERVAL_US and (
            self._temperature > -1 or self._humidity > -1
        ):
            # Less than a second since last read, which is too soon
according
            # to the datasheet
            return

        self._send_init_signal()
        pulses = self._capture_pulses()
        buffer = self._convert_pulses_to_buffer(pulses)
        self._verify_checksum(buffer)

        self._humidity = buffer[0] + buffer[1] / 10
        self._temperature = buffer[2] + buffer[3] / 10
        self._last_measure = utime.ticks_us()

    @property
    def humidity(self):
        self.measure()
        return self._humidity

    @property
    def temperature(self):

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        self.measure()
        return self._temperature

def _send_init_signal(self):
    self._pin.init(Pin.OUT, Pin.PULL_DOWN)
    self._pin.value(1)
    utime.sleep_ms(50)
    self._pin.value(0)
    utime.sleep_ms(18)

@micropython.native
def _capture_pulses(self):
    pin = self._pin
    pin.init(Pin.IN, Pin.PULL_UP)

    val = 1
    idx = 0
    transitions = bytearray(EXPECTED_PULSES)
    unchanged = 0
    timestamp = utime.ticks_us()

    while unchanged < MAX_UNCHANGED:
        if val != pin.value():
            if idx >= EXPECTED_PULSES:
                raise InvalidPulseCount(
                    "Got more than {}
pulses".format(EXPECTED_PULSES)
                )
            now = utime.ticks_us()
            transitions[idx] = now - timestamp
            timestamp = now
            idx += 1

            val = 1 - val
            unchanged = 0
        else:
            unchanged += 1
    pin.init(Pin.OUT, Pin.PULL_DOWN)
    if idx != EXPECTED_PULSES:
        raise InvalidPulseCount(
            "Expected {} but got {}
pulses".format(EXPECTED_PULSES, idx)
        )
    return transitions[4:]

def _convert_pulses_to_buffer(self, pulses):
    """Convert a list of 80 pulses into a 5 byte buffer
    The resulting 5 bytes in the buffer will be:
    0: Integral relative humidity data
    1: Decimal relative humidity data
    2: Integral temperature data
    3: Decimal temperature data
    4: Checksum
    """

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# Convert the pulses to 40 bits
binary = 0
for idx in range(0, len(pulses), 2):
    binary = binary << 1 | int(pulses[idx] > HIGH_LEVEL)

# Split into 5 bytes
buffer = array.array("B")
for shift in range(4, -1, -1):
    buffer.append(binary >> shift * 8 & 0xFF)
return buffer

def _verify_checksum(self, buffer):
    # Calculate checksum
    checksum = 0
    for buf in buffer[0:4]:
        checksum += buf
    if checksum & 0xFF != buffer[4]:
        raise InvalidChecksum()
```